# CppAD's Abs-normal Representation 

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## Non-Smooth Functions

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$a(x)$
Let $s$ be number of $|\cdot|$ in $f$. We define $a: \mathbf{R}^{n} \rightarrow \mathbf{R}^{s}$ where $a_{i}(x)$ is the result for the $i$-th absolute value.

## Smooth Functions

$z(x, u)$
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$g(x, u)$
The function $g: \mathbf{R}^{n+s} \rightarrow \mathbf{R}^{m+s}$ is defined by

$$
g(x, u)=\left[\begin{array}{l}
y(x, u) \\
z(x, y)
\end{array}\right]
$$

Approximating $a(x)$

$$
z[\hat{x}](x, u)=z(\hat{x}, a(\hat{x}))+\partial_{x} z(\hat{x}, a(\hat{x}))(x-\hat{x})+\partial_{u} z(\hat{x}, a(\hat{x}))(u-a(\hat{x}))
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Note that $z_{0}(x, u)$ does not depend on $u$ :

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& +\sum_{j<i} \partial_{u(j)} z_{i}(\hat{x}, a(\hat{x}))\left(a_{j}[\hat{x}](x)-a_{j}(\hat{x})\right) \mid
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a(x) & =a[\hat{x}](x)+o(x-\hat{x})
\end{aligned}
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## Representation

f.abs_normal_fun(g, a)

Given the ADFun<Base> object f for $f(x)$, this creates the two ADFun<Base> objects $g$, a for $g(x, u)$ and $a(x)$ respectively.

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## Advantages

Any AD operation can be computed for the smooth function g ; e.g., any order forward and reverse mode, sparsity patterns, and sparse derivatives.

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f(x)=y[\hat{x}](x, a[\hat{x}](x))+o(x-\hat{x})
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abs_eval(n, m, s, g-hat , g_jac , delta_x)
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- delta x is $x-\hat{x}$


## abs_min_linear

Problem
minimize $\tilde{f}(x)=y[\hat{x}](x, a(\hat{x}))$ w.r.t $x$ subject to $-b \leq x \leq b$ using the assumption that $\tilde{f}(x)$ is convex.

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4. If change in $x$ for this this iteration is small, return $x$ as solution. Otherwise, goto step 2.
