

# Regularization of linear descriptor systems

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Berlin, June 30, 2015

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$$\boxed{\frac{d}{dt}Ex(t) = Ax(t) + Bu(t)} \quad [E, A, B]$$

$$E, A \in \mathbb{R}^{\ell \times n}, B \in \mathbb{R}^{\ell \times m}$$

**Aim:**  $[E, A, B] \rightsquigarrow [\hat{E}, \hat{A}, \hat{B}]$   
 s.t.  $s\hat{E} - \hat{A}$  is regular

1. approach: state feedback
2. approach: behavioral equivalence
3. approach: 1. + 2. + permutation

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## Some basic notions

$sE - A$  is **regular**, if  $\ell = n$  and  $\det(sE - A) \in \mathbb{R}[s] \setminus \{0\}$

regular  $sE - A$  has **index**  $\nu \in \mathbb{N}_0$ , if

$$S(sE - A)T = \begin{bmatrix} sI_r - J & 0 \\ 0 & sN - I_{n-r} \end{bmatrix},$$

$$\text{then } \nu := \begin{cases} 0, & \text{if } r = n, \\ \min \{ k \in \mathbb{N}_0 \mid N^k = 0 \}, & \text{if } r < n \end{cases}$$

**augmented Wong sequences:**

$$\mathcal{V}_0 := \mathbb{R}^n, \quad \mathcal{V}_{i+1} := A^{-1}(E\mathcal{V}_i + \text{im } B), \quad i \geq 0, \quad \mathcal{V}^* := \bigcap_{i \geq 0} \mathcal{V}_i$$

$$\mathcal{W}_0 := \{0\}, \quad \mathcal{W}_{i+1} := E^{-1}(A\mathcal{W}_i + \text{im } B), \quad i \geq 0, \quad \mathcal{W}^* := \bigcup_{i \geq 0} \mathcal{W}_i$$

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## Approach 1: State feedback

**Here:**  $\ell = n$ ,  $u(t) = Fx(t)$  for some  $F \in \mathbb{R}^{m \times n}$

$$\frac{d}{dt}Ex(t) = (A + BF)x(t)$$

**Thm.** [Bunse-Gerstner et al. '92]:

$\exists F \in \mathbb{R}^{m \times n}$  :  $sE - (A + BF)$  is regular and has index  $\leq 1$

$\iff [E, A, B]$  is impulse controllable ( $\text{im } E + A \ker E + \text{im } B = \mathbb{R}^n$ )

**Thm.:**  $\exists F \in \mathbb{R}^{m \times n}$  :  $sE - (A + BF)$  is regular

$\iff \dim(E\mathcal{V}^* + \text{im } B) = \dim \mathcal{V}^*$  [Özçaldiran/Lewis '90]

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$\iff \text{rk}_{\mathbb{R}(s)}[sE - A, B] = n$  [Duan/Zhang '03]



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**Def.:**  $[E, A]$  is *autonomous*, if

$$\frac{d}{dt}Ex(t) = Ax(t) \wedge Ex(0) = 0 \implies x = 0$$

**Lemma:**

$$sE - A \text{ is regular} \iff \ell = n \wedge [E, A] \text{ is autonomous}$$

**Thm.** [Fletcher '86]:

$$\exists F \in \mathbb{R}^{m \times n} : [E, A + BF] \text{ is aut.} \iff \text{rk}_{\mathbb{R}(s)}[sE - A, B] \geq n$$

**Thm.** [B./Reis '15]:

$$\begin{aligned} & \exists F \in \mathbb{R}^{m \times n} : [E, A + BF] \text{ is autonomous} \\ \iff & \text{rk}_{\mathbb{R}(s)}[sE - A, B] \geq n \\ \iff & \dim(E\mathcal{V}^* + \text{im } B) \geq \dim \mathcal{V}^* \\ \iff & \dim(A\mathcal{W}^* + \text{im } B) \geq \dim \mathcal{W}^*. \end{aligned}$$

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## Approach 2: Behavioral equivalence

**Example:**

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \dot{x}(t) = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} x(t) \stackrel{\text{beh.}}{\iff} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \dot{x}(t) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} x(t)$$

$$s \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ is regular}$$

**Def.:** The *behavior* of  $[E, A, B]$  is

$$\mathfrak{B}_{[E,A,B]} = \{ (x, u) \in C^\infty \times C^\infty \mid E\dot{x}(t) = Ax(t) + Bu(t) \}.$$

Two systems  $[E_i, A_i, B_i]$ ,  $i = 1, 2$ , are *behaviorally equivalent* ( $[E_1, A_1, B_1] \simeq_{\mathfrak{B}} [E_2, A_2, B_2]$ ), if

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**Def.:**  $[E, A, B]$  is *minimal*, if

$\forall k \in \{1, \dots, \ell\} \forall [\tilde{E}, \tilde{A}, \tilde{B}]$  with  $k$  rows :

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## Approach 3: Combination of 1 and 2 + permutation

Feedback transformation of  $[E, A, B]$ :

$$S[sE - A, -B] \begin{bmatrix} T & 0 \\ F & V \end{bmatrix}$$

**Lemma:**  $[E_1, A_1, B_1] \simeq_{\mathfrak{B}} [E_2, A_2, B_2] \iff \exists U(s) \in \mathbf{Gl}_{\ell}(\mathbb{R}[s]) :$

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Behavioral and feedback transformation of  $[E, A, B]$ :

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### Example:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \dot{x}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} x(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t)$$

### Approaches 1 and 2 do not work!

$x_2, x_3$  are free  $\rightsquigarrow x_2, x_3$  are inputs in the behavioral framework

$u = 0$   $\rightsquigarrow u$  is a state in the behavioral framework

### Permutation:

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} \dot{x}_1(t) \\ \dot{u}(t) \end{pmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x_1(t) \\ u(t) \end{pmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} x_2(t) \\ x_3(t) \end{pmatrix}$$

$s \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$  is regular and has index 1

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**Thm.** [B./Reis '15]:

$\exists U(s) \in \mathbf{GL}_\ell(\mathbb{R}[s])$ ,  $T \in \mathbf{GL}_n(\mathbb{R})$ ,  $V \in \mathbf{GL}_m(\mathbb{R})$ ,  $F \in \mathbb{R}^{m \times n}$  and a permutation matrix  $P \in \mathbf{GL}_{n+m}(\mathbb{R})$  such that

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where  $s\hat{E} - \hat{A} \in \mathbb{R}[s]^{\hat{n} \times \hat{n}}$  is regular and has index at most 1

- $[\hat{E}, \hat{A}, \hat{B}]$  is minimal
- explicit construction of transformation matrices using feedback canonical form [Loiseau et al. '91]
- the subsystem  $[\hat{E}, \hat{A}, \hat{B}]$  is fully determined by the augmented Wong sequences

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$$[sE - A, -B]$$

$$S_1 B = \begin{bmatrix} 0 \\ B_2 \end{bmatrix}$$

$$S_1[sE - A, -B] = \left[ \begin{array}{c|c} sE_1 - A_1 & 0 \\ \hline sE_2 - A_2 & -B_2 \end{array} \right]$$

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Staircase form [Beelen/Van Dooren '88a]:

$$S_2(sE_1 - A_1)T_2 = \left[ \begin{array}{cccc} sE_\eta - A_\eta & 0 & 0 & 0 \\ * & sE_\infty - A_\infty & 0 & 0 \\ * & * & sE_f - A_f & 0 \\ * & * & * & sE_\varepsilon - A_\varepsilon \end{array} \right]$$

- 1  $E_\eta, A_\eta \in \mathbb{R}^{l_\eta \times n_\eta}$ ,  $l_\eta > n_\eta$ , are such that  $\text{rk}_{\mathbb{C}}(\lambda E_\eta - A_\eta) = n_\eta$  and  $\text{rk } E_\eta = n_\eta$ ;
- 2  $E_\infty, A_\infty \in \mathbb{R}^{n_\infty \times n_\infty}$ ,  $A_\infty$  is invertible and  $A_\infty^{-1}E_\infty$  is nilpotent;
- 3  $E_f, A_f \in \mathbb{R}^{n_f \times n_f}$  and  $E_f$  is invertible;
- 4  $E_\varepsilon, A_\varepsilon \in \mathbb{R}^{l_\varepsilon \times n_\varepsilon}$ ,  $l_\varepsilon < n_\varepsilon$ , are such that  $\text{rk}_{\mathbb{C}}(\lambda E_\varepsilon - A_\varepsilon) = l_\varepsilon$  and  $\text{rk } E_\varepsilon = l_\varepsilon$ .

$$S[sE-A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{cccc|c} sE_\eta - A_\eta & 0 & 0 & 0 & 0 \\ * & sE_\infty - A_\infty & 0 & 0 & 0 \\ * & * & sE_f - A_f & 0 & 0 \\ * & * & * & sE_\varepsilon - A_\varepsilon & 0 \\ * & * & * & * & -B_2 \end{array} \right]$$

Staircase form [Beelen/Van Dooren '88a]:

$$S_2(sE_1 - A_1)T_2 = \left[ \begin{array}{cccc} sE_\eta - A_\eta & 0 & 0 & 0 \\ * & sE_\infty - A_\infty & 0 & 0 \\ * & * & sE_f - A_f & 0 \\ * & * & * & sE_\varepsilon - A_\varepsilon \end{array} \right]$$

$$S[sE-A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{cccc|c} sE_\eta - A_\eta & 0 & 0 & 0 & 0 \\ * & sE_\infty - A_\infty & 0 & 0 & 0 \\ * & * & sE_f - A_f & 0 & 0 \\ * & * & * & sE_\varepsilon - A_\varepsilon & 0 \\ * & * & * & * & -B_2 \end{array} \right]$$

Unimodular embedding [Beelen/Van Dooren '88b]:

$$U_1(s) := \begin{bmatrix} K & sE_\eta - A_\eta & 0 \\ 0 & * & sE_\infty - A_\infty \end{bmatrix}$$



$$U(s)^{-1}[sE-A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ sE_{31} - A_{31} & sE_f - A_f & 0 & 0 \\ sE_{41} - A_{41} & * & sE_\varepsilon - A_\varepsilon & 0 \\ sE_{51} - A_{51} & * & * & -B_2 \end{array} \right]$$

Unimodular embedding [Beelen/Van Dooren '88b]:

$$U_1(s) := \begin{bmatrix} K & sE_\eta - A_\eta & 0 \\ 0 & * & sE_\infty - A_\infty \end{bmatrix}$$

$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ sE_{31} - A_{31} & sE_f - A_f & 0 & 0 \\ sE_{41} - A_{41} & * & sE_\varepsilon - A_\varepsilon & 0 \\ sE_{51} - A_{51} & * & * & -B_2 \end{array} \right]$$

$$U_2(s) = \begin{bmatrix} I_{l_\eta-n_\eta} & 0 & 0 & 0 & 0 \\ 0 & I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ 0 & -sE_{31} + A_{31} & I_{n_f} & 0 & 0 \\ 0 & -sE_{41} + A_{41} & 0 & I_{l_\varepsilon} & 0 \\ 0 & -sE_{51} + A_{51} & 0 & 0 & I_r \end{bmatrix}$$

$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ 0 & sE_f - A_f & 0 & 0 \\ 0 & * & sE_\varepsilon - A_\varepsilon & 0 \\ 0 & * & * & -B_2 \end{array} \right]$$

$$U_2(s) = \begin{bmatrix} I_{l_\eta-n_\eta} & 0 & 0 & 0 & 0 \\ 0 & I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ 0 & -sE_{31} + A_{31} & I_{n_f} & 0 & 0 \\ 0 & -sE_{41} + A_{41} & 0 & I_{l_\varepsilon} & 0 \\ 0 & -sE_{51} + A_{51} & 0 & 0 & I_r \end{bmatrix}$$

$$U(s)^{-1}[sE-A, -B] \begin{bmatrix} T & 0 \\ 0 & I \end{bmatrix} = \left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -I_{n_\eta+n_\infty} & 0 & 0 & 0 \\ 0 & sE_f - A_f & 0 & 0 \\ 0 & * & sE_\varepsilon - A_\varepsilon & 0 \\ 0 & * & * & -B_2 \end{array} \right]$$

$$E_\varepsilon T_3 = [\Sigma_1, 0], \quad B_2 V_3 = [\Sigma_2, 0]$$

$\Sigma_1, \Sigma_2$  invertible

$$\begin{aligned}
 & U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix} \\
 &= \left[ \begin{array}{cccc|cc}
 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -A_{44} & 0 & 0 \\
 0 & * & * & sE_{54} - A_{54} & -\Sigma_2 & 0
 \end{array} \right]
 \end{aligned}$$

$$E_\varepsilon T_3 = [\Sigma_1, 0], \quad B_2 V_3 = [\Sigma_2, 0]$$

$\Sigma_1, \Sigma_2$  invertible

$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix} \\
 = \left[ \begin{array}{cccc|cc}
 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -A_{44} & 0 & 0 \\
 0 & * & * & sE_{54} - A_{54} & -\Sigma_2 & 0
 \end{array} \right]$$

$$S_4 E_{54} T_4 = \begin{bmatrix} \Sigma_3 & 0 \\ 0 & 0 \end{bmatrix}, \quad S_4 \Sigma_2 V_4 = \begin{bmatrix} \Sigma_{21} & 0 \\ * & \Sigma_{22} \end{bmatrix}$$

$\Sigma_3, \Sigma_{21}, \Sigma_{22}$  invertible

$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix} \\
 = \left[ \begin{array}{ccccc|ccc}
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -\tilde{A}_{44} & -\tilde{A}_{45} & 0 & 0 & 0 \\
 0 & * & * & s\Sigma_3 - \tilde{A}_{54} & -\tilde{A}_{55} & -\Sigma_{21} & 0 & 0 \\
 0 & * & * & -\tilde{A}_{64} & -\tilde{A}_{65} & * & -\Sigma_{22} & 0
 \end{array} \right]$$

$$S_4 E_{54} T_4 = \begin{bmatrix} \Sigma_3 & 0 \\ 0 & 0 \end{bmatrix}, \quad S_4 \Sigma_2 V_4 = \begin{bmatrix} \Sigma_{21} & 0 \\ * & \Sigma_{22} \end{bmatrix}$$

$\Sigma_3, \Sigma_{21}, \Sigma_{22}$  invertible

$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix}$$

$$= \left[ \begin{array}{cccccc|ccc}
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -\tilde{A}_{44} & -\tilde{A}_{45} & 0 & 0 & 0 & 0 \\
 0 & * & * & s\Sigma_3 - \tilde{A}_{54} & -\tilde{A}_{55} & -\Sigma_{21} & 0 & 0 & 0 \\
 0 & * & * & -\tilde{A}_{64} & -\tilde{A}_{65} & * & -\Sigma_{22} & 0 & 0
 \end{array} \right]$$

$$P = \begin{bmatrix} I_{n_\eta+n_\infty+n_f+l_\varepsilon+q} & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & I_{n_\varepsilon-l_\varepsilon-q} & 0 \\
 0 & 0 & I_q & 0 & 0 \\
 0 & I_{r-q} & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & I_{m-r} \end{bmatrix}$$



$$U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix} P$$

$$= \left[ \begin{array}{cccccc|ccc}
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -\tilde{A}_{44} & 0 & 0 & 0 & -\tilde{A}_{45} & 0 \\
 0 & * & * & s\Sigma_3 - \tilde{A}_{54} & 0 & -\Sigma_{21} & -\tilde{A}_{55} & 0 & 0 \\
 0 & * & * & -\tilde{A}_{64} & -\Sigma_{22} & * & -\tilde{A}_{65} & 0 & 0
 \end{array} \right]$$

$$\begin{aligned}
 & U(s)^{-1}[sE - A, -B] \begin{bmatrix} T & 0 \\ 0 & V \end{bmatrix} P \\
 &= \left[ \begin{array}{ccccc|ccc}
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 -I_{n_\eta+n_\infty} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & sE_f - A_f & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & * & s\Sigma_1 - A_{43} & -\tilde{A}_{44} & 0 & 0 & -\tilde{A}_{45} & 0 \\
 0 & * & * & s\Sigma_3 - \tilde{A}_{54} & 0 & -\Sigma_{21} & -\tilde{A}_{55} & 0 \\
 0 & * & * & -\tilde{A}_{64} & -\Sigma_{22} & * & -\tilde{A}_{65} & 0
 \end{array} \right] \\
 &= \left[ \begin{array}{c|c}
 0_{(l_\eta-n_\eta) \times \hat{n}} & 0_{(l_\eta-n_\eta) \times m} \\
 sE_{\text{reg}} - A_{\text{reg}} & -B_{\text{reg}}
 \end{array} \right]
 \end{aligned}$$

$sE_{\text{reg}} - A_{\text{reg}} \in \mathbb{R}[s]^{\hat{n} \times \hat{n}}$  is regular and has index at most one

## Computational aspects

- the algorithm is numerically stable
- the computational complexity, given  $E, A \in \mathbb{R}^{\ell \times n}$ ,  $B \in \mathbb{R}^{\ell \times m}$  is

$$O(\ell^2(\ell + n + m) + n^2(\ell + n) + m^3)$$

- the inverse  $V(s) = U(s)^{-1}$  can be computed [Beelen/Van Dooren '88b]; this requires inversion of a triangular matrix and has a cost of

$$O(q\ell^3),$$

where  $q = \deg V(s)$